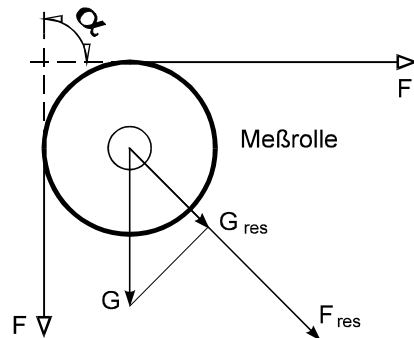


## Radial Force Sensor Series M 1355 – NH and NH-2



- $\alpha$  = angle of contact  
 $F$  = tensile force of the material to be measured  
 $F_{res}$  = resulting force which is measured  
 $G$  = weight of the measuring roller  
 $G_{res}$  = part of the -measuring roller weight- in sphere -direction of the sensor



Radial - Force - Sensors of series M 1355 NH are precise and reliable measuring systems, as well high overload-protected as high in long-time-stability.

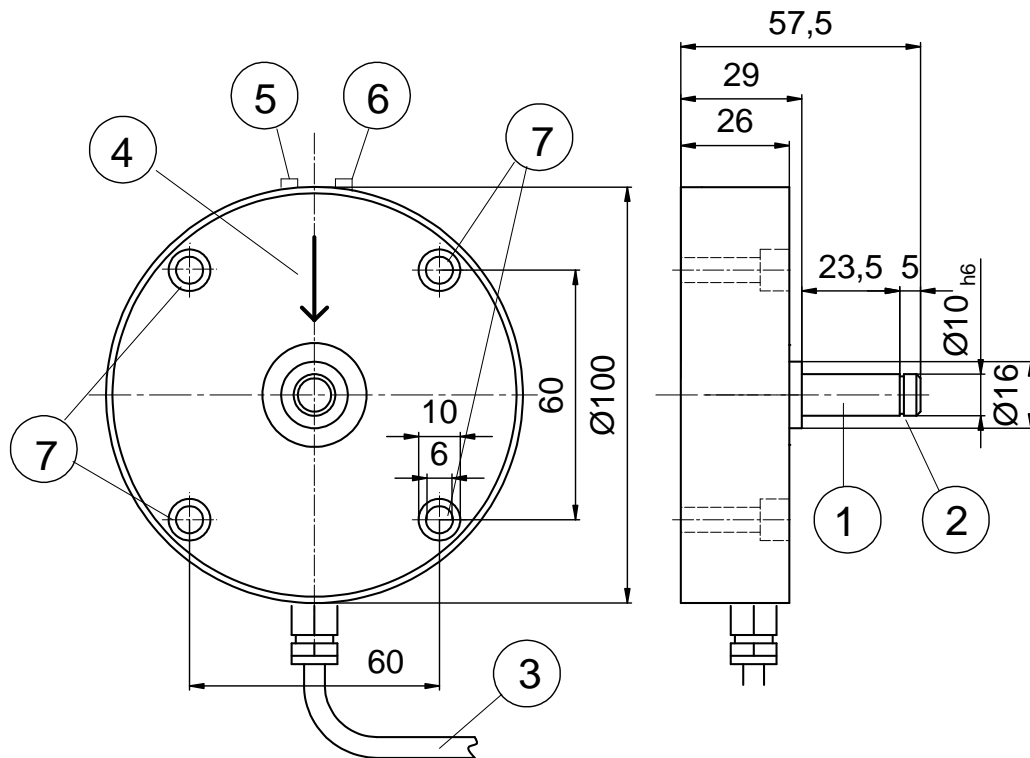
For measuring tensile forces on running material, fit a ball-bearing-mounted roller on the journal-bearing. This measuring roller has to be mounted in a position, that the material which will be measured, will deviate in a defined angle. Here angle of contacts, of the material which is measured - around the measuring-roller, between 3° and 180° are possible. The resulting forces, due to the deviation, are measured by the sensor. The radial force is proportional to the tensile force, in the material which is measured. Corresponding to this radial-force the nominal load of the sensor is to select.

- Application:** measuring tensile forces on running or not running material  
 p.e.: on wires, cables, tapes etc.  
 p.e.: range of centrifugal-forces, in rotating stranding machines
- Characteristics:** extreme space-saving and flat construction, easy mounting  
 equipped with a standard - journal bearing of  $\varnothing 10$  mm  
 realisation the measured data is independent of the width of the used roller
- Nominal loads:** 50 N, 100 N, 200 N, 300 N - others upon request
- Measuring range:** by changing the angle of contact - around the measuring roller -  
 the measuring range is variable
- Measuring principle:** strain-gage, full-bridge, built in amplifier  
 the sensor transforms the - on the measuring roller - active radial forces  
 into a proportional electric signal
- Mounting:** 4 screws M 6
- Connection:** Electrical connection by means of a fixed cable, length 3 m.
- Accessories available:** Connection cable, amplifier with or without indication, rollers

**Technical data :**

**Radial Force Sensor Series M 1355-NH**

Dimensions :



- 1 = Axle ( journal-bearing )
- 2 = Seeger ring A10
- 3 = Connection cable
- 4 = Loading direction
- 5 = Potentiometer to adjust the electrical zero ( Offset )
- 6 = Potentiometer to adjust the gain ( Calibration )
- 7 = Holes to fix the sensor

Realization the measured data via strain-gages, amplifier is built in.  
The desired service voltage must be indicated together with the order.

**Nominal loads:** 50N, 100 N, 300 N - others upon request

<b>Measuring principle:</b>	strain-gage, full-bridge	<b>Coef. of temperature:</b>	
<b>Measuring range:</b>	1 % up to 115% the nom.load	- of the zero	< 0,035 % / °C
<b>Value tolerance:</b>	< ± 0, 2 %	- of the meas. range	< 0,05 % / °C
<b>Overload protection:</b>	5- times up to 10- times depends on the nom.load		

<b>Service voltage:</b>	5 V ± 10%	< 90 mA	<b>Outputsignal:</b>	0 ... ± 10V
	12 V ± 10%	< 70 mA	<b>Output current:</b>	max. 2 mA
	24 V ± 10%	< 30 mA	option: Output current	4 - 20mA
	± 15 V ± 10%	< +20 mA < -10 mA		

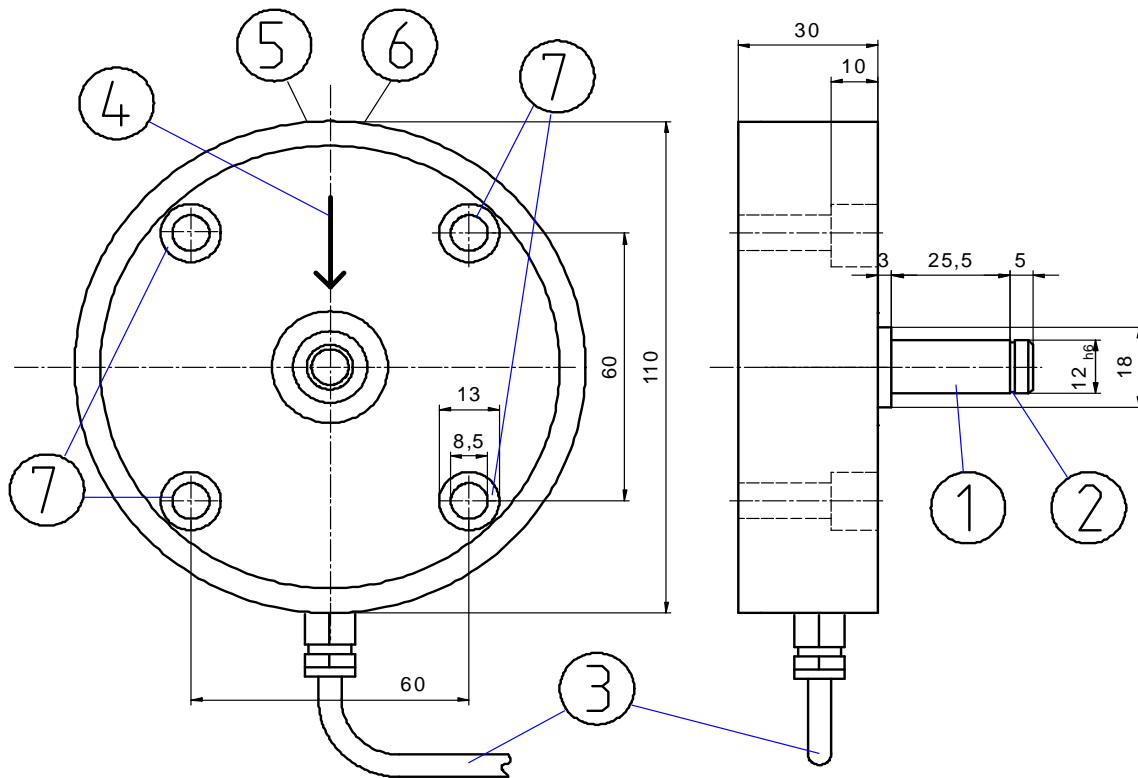
<b>Protection:</b>	IP 50	<b>Adjusting range zero:</b>	± 20% of the nom.load
<b>Charact. of temperature:</b>	+ 5°C ... + 55°C	<b>Adjusting range gain:</b>	± 20% of the nom.load

Adjusting the zero by means of a screw-driver  
Adjusting the gain by means of a screw driver

**Connection cable:** length 3 m, fix connected  
**Delivery:** Sensor with Seegerring A10, Instruction manual

**Technical data**

**Dimensions M 1355- NH-2 :**



- 1 = journal bearing
- 2 = for Seegerring A12
- 3 = connection cable
- 4 = loading - direction

- 5 = Potentiometer to adjust the electrical zero
- 6 = Potentiometer to adjust the gain ( calibration )
- 7 = bore-holes for fixing screws

Realisation the measured data via strain-gages, amplifier is built-in.  
The desired service voltage has to be indicated together with the order.

Nominal loads                    300 N, 500 N, 600N or 1000N -- others upon request

Measuring principle	strain-gage, full-bridge		
Measuring range	1 % up to 115% of the nom.load	Coef. of temperature	
Max. Error in line.	< ± 0, 2 %	- of the zero	< 0,035 % / °C
Overload protection	5 to 10 times	- of the meas. range	< 0, 05 % / °C
	Depending the nom.load		

Service voltage	5 V ± 10%	< 100 mA	Output signal	0 ... ± 10V
	12 V ± 10%	< 70 mA	Output current	max. 2 mA
	24 V ± 10%	< 40 mA	option: Output current	4 - 20mA

Protection	IP 50	Adjusting range zero	± 20% of the nom.load
Charact.range of temp.	+ 5°C ... + 55°C	Adjusting range calibration	± 20% of the nom.load

Adjusting the zero                    by means of a screw-driver  
Adjusting the gain                    by means of a screw driver

Connection cable:                    length 5 m, fix connected  
Delivery:                                Sensor with Seegerring A12, Instruction manual