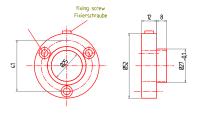


# Clamping devices for rollers and sensors



#### **Z 1190** Ø 24 mm, hold on forces 50 N

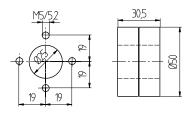
This clamping device permits a fast and safe fixing of cylindrical bodies having a diameter of 24 mm, p.e. Tensometric radial force sensor series M 1191, M 1192, M 1391, M 1392





### **Z 1191** Ø 24 mm, hold on forces 500 N

It permits to suit the sensor infinitely variable in height and angle, into the running process. By means of 4 inside hexagon screws the sensor can be fixed in the measuring position. To fix the clamping device it needs only 4 bore-holes, Ø 5,2 mm or 4 thread-holes M5 and a bore hole Ø 25 mm for the sensor.



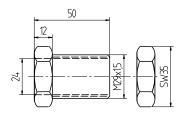


## **Z 1391** Ø 24 mm, hold on forces 500 N

To fix clamping devices and sensors, it is only necessary to have a bore-hole of approx.  $\varnothing$  30mm in the machine-panel.

In this bore-hole, the clamping device is fixed by means of its two nuts.

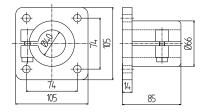
Put in the sensor into the clamping-device Z 1391. By countering the two nuts, the bore-hole of the clamping-device Z 1391 reduces itself. by radial forces the sensor clamps are unremovable





## **Z 40 A** Ø 40 mm, hold on forces 5000 N

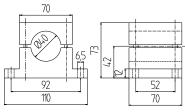
To fix rollers and sensors having a diameter of 40 mm in a mounting-panel.





### **Z 40 B** Ø 40 mm, hold on forces 5000 N

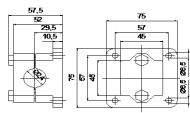
To fix rollers and sensors having a diameter of 40 mm on a holder.





#### **Z 25 B** Ø 25 mm, hold on forces 200 N

To fix rollers and sensors having a diameter from 24 mm up to 25 mm on a holder.



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